	Class: XI SESSION:2023-2024 MARKING SCHEME HBSE SAMPLEQUESTIONPAPER(THEORY) SUBJECT:PHYSICS	
Q.no		Marks
-	SECTIONA	
1	(iii) 8h/9	1
2	(ii) zero	1
3	(ii) 45	1
4	(iii) 7200 N	1
5	(i)Opposing force	1
6	(iv) pascal	1
7	(i) 0	1
8	(i)F	1
9	(ii) B	1
10	(iii) zero	1
11	(iv) 10 ⁷ Nm ⁻²	1
12	(iii) Hook's law	1
13	(iv) 8Q	1
14	(i)J/kg	1
15	(a)	1
16	(d)	1
17	(d)	1
18	(b)	1
	SECTIONB	
19	$P = \frac{a^3 b^2}{\left(\sqrt{c}d\right)}.$ $\frac{\Delta P}{P} = \frac{3\Delta a}{a} + \frac{2\Delta b}{b} + \frac{1}{2}\frac{\Delta c}{c} + \frac{\Delta d}{d}$	1/2
	$ P = a = b = 2 c = d $ $ \left(\frac{\Delta P}{P} \times 100\right) \% = \left(3 \times \frac{\Delta a}{a} \times 100 + 2 \times \frac{\Delta b}{b} \times 100 + \frac{1}{2} \times \frac{\Delta c}{c} \times 100 + \frac{\Delta d}{d} \times 100\right) \% $	1/2
	$= 3x1 + 2x3 + \frac{1}{2}x4 + 2$	1/2
	= 3 + 6 + 2 + 2	1/
	= 13 %	1/2
	Percentage error in $P = 13 \%$	

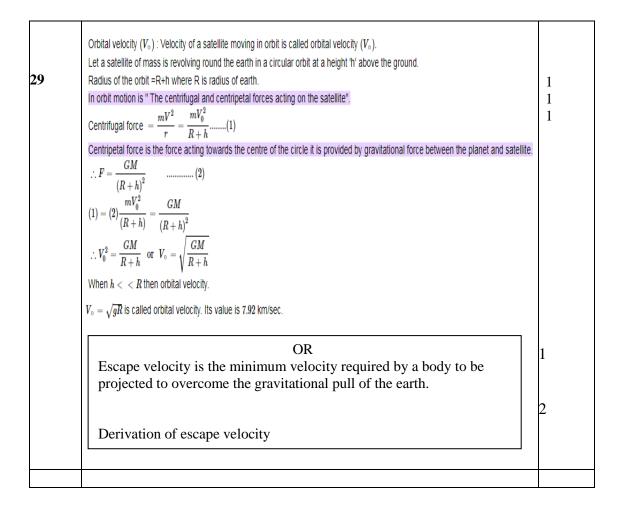
20	$\frac{\text{Given unit}}{\text{New unit}} = \left(\frac{M_1}{M_2}\right)^2 \left(\frac{L_1}{L_2}\right)^2 \left(\frac{T_1}{T_2}\right)^2$	
	Dimension formula of heat = $[M^{1}L^{2}T^{-2}]$	1⁄2
	$\therefore \mathbf{x} = 1, \mathbf{y} = 2, \mathbf{z} = 2$	
	Since $M_1 = 1 \text{kg}$, $L_1 = 1 \text{m}$, $T_1 = 1 \text{s}$	1⁄2
	and $M_2 = \alpha \text{ kg}$, $L_2 = \beta \text{ m}$, $T_2 = \gamma \text{ s}$	
	As 1 calorie = 4.2 Joule	
	and 1 Joule = $1 \text{kg} \text{ m}^2 \text{s}^{-2}$	1⁄2
	$\Rightarrow \frac{\text{calorie}}{\text{New unit}} = 4.2 \left(\frac{1\text{kg}}{\alpha\text{kg}}\right)^1 \left(\frac{1\text{m}}{\beta\text{m}}\right)^2 \left(\frac{1\text{s}}{\gamma\text{s}}\right)^{-2}$	
	\therefore Calorie = $4.2\alpha^{-1}\beta^{-2}\gamma^2$ New unit	1/2
	A conservative force exists when the work done by that force on an object is independent of the object's path. Instead, the work done by a conservative force depends only on the end points of the motion. An example of a conservative force is gravitational force, electrostatic force.	2
	Or	
	Elastic potential energy is energy stored as a result of applying a force to deform an elastic object.	1
	Elastic potential energy= ²³ ¹ / ₂ 1/2 kx ²	1

22	A colligion in which there is checkets he loss Of the stic	1
	A collision in which there is absolutely no loss Of kinetic	
	energy is called elastic collision.	
	Characteristics: (any two)	
	1. The linear momentum is conserved.	1⁄2
	2. Total energy of the system is conserved.	
	3. Kinetic energy is conserved.	1/2
	4. Forces involved during elastic collisions must be	
	conservative forces.	
	OR	
	The ratio of relative velocity after collision to the relative velocity	2
	between two objects before their collision is known as the	
	coefficient of restitution.	
23	Pascal's law is any pressure applied to a fluid inside a closed	1+1
	system will transmit that pressure equally in all directions	
	throughout the fluid.	
	Hydraulic brake,Hydraulic jack	
24	As temperature levels change, so does the air pressure in your tyres. It's the same as when you drive at higher	
	speeds for an extended period: the tyre warms, and the air	
	within expands and increases pressure	2

25	Length of the steel wire, $1 = 12m$	
	Mass of the steel wire, $m = 2.10 \text{kg}$	
	Velocity of the transverse wave, $v = 343$ m/s	
	Mass per unit length, μ = m/l = 2.10/12 = 0.175 kg m^{-1}	
	For Tension T, velocity of the transverse wave can be obtained using the	
	relation:	
	$v = \sqrt{\frac{T}{\mu}}$	1
	$\therefore T = v^2 \mu$	1
	$= (343)^2 \times 0.175 = 20588.575 \simeq 2.06 \times 10^4 $ N.	-
	SECTIONC	
26	Let $AB = s$, time takemn to go form A to B,	1
	$t=rac{s}{40}h$	1
	and time taken to go form B to $A, t_2 = rac{s}{30}h$	
	\therefore total time taken =	
	$t_1+t_2=rac{S}{40}+rac{s}{30}=rac{(3+4)s}{120}=rac{7s}{120}h$	1
	Total distance travelled $= s + s = 2s$	
	$\therefore \text{"Average speed"} = \frac{\text{total distance travelled}}{\text{total time taken}}$	1
	$=rac{2s}{7s/120}=rac{120 imes 2}{7}=34.3 km/h$	
27	Consider a system of two particles of masses m ₁ and m ₂ located at A and B respectively.	
	$\vec{OA} = \vec{r_1}$	1
	and $ec{OB}=ec{r_2}$	1
	$ \begin{array}{c} $	
	2	
	Let C be the position of centre of mass of the system of two particles. It would lie on the line joining A and B. Let $\vec{OC} = \vec{r}$ be the position vector of mass.	
	To evaluate $ec{r}$, suppose $ec{v_1} \& ec{v_2}$ be the velocities of particles m_1 and m_2 respectively at any instant t	
	then, $v_1=rac{dr_1}{dt}$	
	and $v_2=rac{dr_2}{dt}\ldots\ldots(1)$	
	Let]

 $f_1 = external force on m_1$ $f_2 = external force on m_2$ F_{12} = internal force of m_1 due to m_2 1 F_{21} = internal force on m_2 due to m_1 Linear momentum of particle m₁ $\vec{p_1} = m_1 \vec{v_1} \dots \dots (2)$ According to Newton's second law total force acting on this particle which is ($\vec{f}_1 + \vec{F}_{12}$ $\frac{d\vec{p_1}}{dt} = \vec{f_1} + \vec{F}_{12}$ Using (2), $rac{d}{dt}(m_1ec{v_1}) = ec{f_1} + ec{F_{12}}.....(3)$ where \vec{f} = total external force on the system of two particles. Using (1), $\frac{\frac{d}{dt}\left[m_1\frac{d\vec{r_1}}{dt} + m_2\frac{d\vec{r_2}}{dt}\right] = \vec{f}$ $\frac{\frac{d}{dt}\left[\frac{d}{dt}(m_1\vec{r_1} + m_2\vec{r_2})\right] = \vec{f}$ 1 Or $\frac{d^2}{dt^2}\vec{r}(m_1\vec{r_1} + m_2\vec{r_2}) = \vec{f}$ Multiplying numerator and denominator of left side by $(m_1 + m_2)$, $(m_1 + m_2) \frac{d^2}{dt^2} \vec{r} \frac{(m_1 \vec{r_1} + m_2 \vec{r_2})}{(m_1 + m_2)} = \vec{f}$...(6) Let us put $\frac{m_1 \vec{r_1} + m_2 \vec{r_2}}{(m_1 + m_2)} = \vec{r} \qquad \dots (7)$ $(m_1+m_2)rac{d^2}{dt^2}ec{r}=ec{f}\dots(8)$ This is the equation of motion of total mass (m₁ + m₂) supposed to be concentrated at a point whose position of vectors is \vec{r} under the effect of total force \vec{f} . Now from (7), $(m_1 + m_2)\vec{r} = m_1\vec{r_1} + m_2\vec{r_2}$

		1.5
		1.5
28	The moment of inertia of a rigid composite system is the sum of the moments of inertia of its component subsystems (all taken about the same axis) . We know, kinetic energy $(E) = \frac{1}{2}mv^2$	1
	As $v = \omega r$ So $E = \frac{1}{2}mr^2\omega^2 \Rightarrow E = \frac{1}{2}I\omega^2$ [$\therefore I = mr^2$] which is required relationship between kinetic energy of rotation and moment of inertial	2

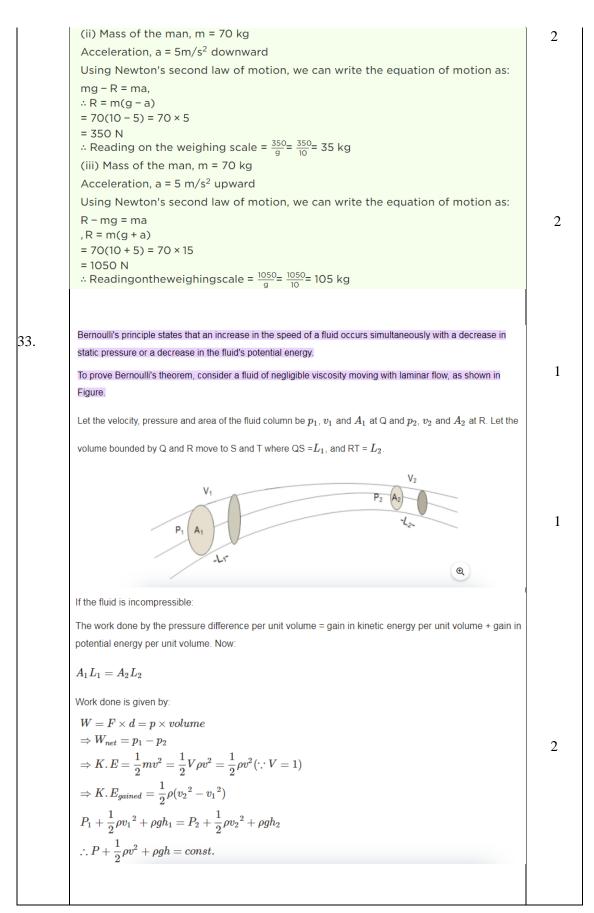


30	An isothermal process is a thermodynamic process, in which the	1
	temperature of the system remains constant:	
	$\Delta T=0.$	
	Suppose 1 mole of gas is enclosed in isothermal container. Let P_1 , V_1 , T be	
	initial pressure, volumes and temperature. Let expand to volume V $_2$ &	
	pressure reduces to P $_2$ & temperature remain constant. Then, work done is given by $W = \int dW$	
	$W = \int_{V_1}^{V_2} P dV$ as $PV = RT$ (n = mole)	1
	$P = \frac{RT}{V}$	
	$W = \int_{V_1}^{V_2} \frac{RT}{V} dV$ $W = RT \int_{V_1}^{V_2} \frac{dV}{V}$	
	$= \operatorname{RT}[\operatorname{InV}]_{V_1}^{V_2}$	
	$= RT [InV_2 - InV_1]$	
	$W = RTIn \frac{V_2}{V_1}$	
	$W = 2.303 \text{RT} \log_{10} \frac{\text{v}^2}{\text{V}_1}$	1

	SECTION D	
31	(i) Let H be the maximum height reached by the projectile in time t_1 For vertical motion, The initial velocity = $u \sin \theta$ The final velocity = 0	
	Acceleration = $-g$ \therefore using, $v^2 = u^2 + 2as$ $0 = u^2 \sin^2 \theta - 2gH$	1
	$2gH = u^{2} \sin^{2} \theta$ $H = \frac{u^{2} \sin^{2} \theta}{2g}$	1
	 (ii) Let t, be the time taken by the projectile to reach the maximum height H. For vertical motion, initial velocity = u sin θ Final velocity at the maximum height = 0 	
	Acceleration $a = -g$ Using the equation $v = u + at_1$	1
	$0 = u \sin \theta - gt_1$ $gt_1 = u \sin \theta$ $t_1 = \frac{u \sin \theta}{2}$	1

	Let t_2 be the time of descent.	
	But $t_1 = t_2$	
	i.e. time of ascent= time of descent.	
	\therefore Time of flight T = t ₁ + t ₂ = 2t ₁	
	$\therefore T = \frac{2u \sin \theta}{g}$ (iii) Let R be the range of the projectile in a time T. This is covered by the projectile with a constant velocity $u \cos \theta$. Range=horizontal component of velocity \times Time of flight i.e, R = $u \cos \theta$.T R = $u \cos \theta$. $\frac{2u \sin \theta}{g}$ R = $\frac{u^2 \sin 2\theta}{g}$ $x = \frac{u^2 \sin 2\theta}{g}$	
	OR The parallelogram law of vector addition states that if two vectors are considered to be the two adjacent sides of a parallelogram with their tails meeting at the common point, then the diagonal of the parallelogram originating from the common point will be the resultant vector.	1
	Derivation for resultant	
32	Newton's second law of motion states that "Force is equal to the rate of change of momentum. For a constant mass, force equals mass times acceleration.	2

$a = \frac{(v - u)}{t} = \frac{(0 - 10)}{4} = -2.5 \text{m/s}^2$ The negative sign indicates that the velocity of the three-wheeler is decrea with time. Using Newton's second law of motion, the net force acting on the three-wheeler can be calculated as: $F = Ma = 465 \times (-2.5) = -1162.5 \text{N}$ The negative sign indicates that the force is acting against the direction of motion of the three-wheeler. OR (i) Mass of the man, m = 70 kg Acceleration, a = 0 Using Newton's second law of motion, we can write the equation of motion as: $R - mg = ma$ Where, ma is the net force acting on the man. As the lift is moving at a uniform speed, acceleration a = 0 $R = mg = 70 \times 10 = 700 \text{ N}$	Initial speed of the three-wheeler, $u = 36$ km/h = 10m/s	
Mass of the three-wheeler, $m = 400 \text{ kg}$ Mass of the driver, $m' = 65 \text{ kg}$ Total mass of the system, $M = 400 + 65 = 465 \text{ kg}$ Using the first law of motion, the acceleration (a) of the three-wheeler can calculated as: v = u + at $a = \frac{(v - u)}{t} = \frac{(0 - 10)}{4} = -2.5 \text{m/s}^2$ The negative sign indicates that the velocity of the three-wheeler is decrea with time. Using Newton's second law of motion, the net force acting on the three- wheeler can be calculated as: $F = Ma = 465 \times (-2.5) = -1162.5 \text{N}$ The negative sign indicates that the force is acting against the direction of motion of the three-wheeler. OR (1) Mass of the man, $m = 70 \text{ kg}$ Acceleration, $a = 0$ Using Newton's second law of motion, we can write the equation of motion as: R - mg = ma Where, ma is the net force acting on the man. As the lift is moving at a uniform speed, acceleration $a = 0$ $\approx R = mg$ $= 70 \times 10 = 700 \text{ N}$	Final speed of the three-wheeler, $v = 0 \text{ m/s}$	
Mass of the driver, m' = 65kg Total mass of the system, M = 400 + 65 = 465 kg Using the first law of motion, the acceleration (a) of the three-wheeler can calculated as: v = u + at $a = \frac{(v - u)}{t} = \frac{(0 - 10)}{4} = -2.5 \text{m/s}^2$ The negative sign indicates that the velocity of the three-wheeler is decrea with time. Using Newton's second law of motion, the net force acting on the three- wheeler can be calculated as: $F = Ma = 465 \times (-2.5) = -1162.5 \text{N}$ The negative sign indicates that the force is acting against the direction of motion of the three-wheeler. OR (i) Mass of the man, m = 70 kg Acceleration, a = 0 Using Newton's second law of motion, we can write the equation of motion as: R - mg = ma Where, ma is the net force acting on the man. As the lift is moving at a uniform speed, acceleration a = 0 $k = mg = 70 \times 10 = 700 \text{ N}$	Time, t = 4s	
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	-	



Bernoulli's equation LIMITATION (ANY TWO) [1] the flow must be steady, i.e., the flow parameters (velocity, density, etc) at any point cannot change with time [2] the flow must be incompressible – even though pressure varies, the density must remain constant along with a streamline and [3] friction by viscous forces must be negligible.	1/2+
Terminal velocity is defined as the highest velocity attained by an object falling through a fluid	1
Derivation for terminal velocity	2

	SECTION E	
34	 1. 1.38x10⁻²³ joule per Kelvin. 2. P=1/3pv² 3. The law of energy equipartition states that the total energy for every dynamic system in thermal equilibrium is evenly shared among the degrees of freedom. Or Degree of Freedom 	1 1 2
35	1. b) longitudinal waves	1
	2. c) Any medium even through vacuum	1
	3. a longitudinal wave, the medium or the channel moves in the same direction with respect to the wave. Here, the movement of the particles is from left to right and forces other particles to vibrate. In a transverse wave the medium or the channel moves perpendicular to the direction of the wave.	2
	OR	
	Proof of $V = \nu \lambda$	